

On Existence of Unique Solution by First Order System

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We consider the following system of simultaneous differential equations in terms of four components u, v, w and x and a vector function θ .

$$\begin{aligned}u'' + lv + mw + nx &= \lambda u \\ u - v'' + pw + qx &= \mu v \\ mu + pv + iw' + r(x) &= vw \\ nu + qv + rw - ix' &= \eta x\end{aligned}$$

where u, v, w, x are functions of t , l, m, n, p, r are real valued continuous functions of t , λ, μ, v, η are parameters which may be real or complex, $t \in [a, b]$, $i = \sqrt{-1}$, and dashes denote derivatives w.r.t. t .

Theorem: The system (1.1) of differential equations yields (admits) a unique solution

$$\theta(t) = (uvwx)^t(t)$$

satisfying the initial conditions

$$\begin{aligned}u^t(\alpha) &= A_1 \\ A^{(t)}(\alpha) &= B_1 \\ w(\alpha) &= C_0 \\ x(\alpha) &= D_{t^2}\end{aligned}$$

and

where $A_1, B_t(x=0,1), C_0, D_0$ are arbitrary constants (real) or complex) not all vanishing simultaneously, T denotes transpose (s) denotes sih derivatives w.r.t. t and $\alpha \in [a, b]$.

Proof. The system of differential equations (1.1) and set of initial conditions (1.2) may be alternatives written as:

$$\begin{aligned}u'' &= -lv - mw - nx + \lambda u \\ v'' &= lu + pw + qx - \mu v \\ w' &= imu + ipv + irx - ivw' \\ x' &= inu - iqv - irw + i\eta x \\ (u(\alpha), u(\alpha), v(\alpha), w(\alpha), x(\alpha)) &= (A_0 A_1 B_0 B_1 C_0 D_0)\end{aligned}$$

Futher for a vector V let V^T denote the transpose of V and

$$V^T = (uu'vv'wx)$$

where dashes denote derivatives w.r.t. t , then (1.3) and (1.4) have their respective equivalent form as:

$$V^T(t) = F(T)V(T)$$

and

$$V(\alpha) = (A_0 A_1 B_0 B_1 C_0 D_0)^T$$

Where

$$F(t) = \begin{bmatrix} 0 & 1 & 0 & 0 & 0 & 0 \\ \lambda & 0 & -\lambda & 0 & -m & -n \\ 0 & 0 & 0 & 1 & 0 & 0 \\ 1 & 0 & -\mu & 0 & p & q \\ im & 0 & ip & 0 & iv & ir \\ -in & 0 & iq & 0 & -ir & i\eta \end{bmatrix}$$

Since V and F both are complex, hence we can write them as

$$V = V_1 + iV_2$$

and

$$F = F_1 + iF_2$$

Where V_1, V_2 and F_1, F_2 are real matrices.

With the help of (1.6) we get from (1.5)

$$w'(t) = \begin{bmatrix} F_1 & -F_2 \\ F_2 & F_1 \end{bmatrix} w(t)$$

Where

$$w = \begin{bmatrix} V_1 \\ V_2 \end{bmatrix} w_0 = \begin{bmatrix} V_1(\alpha) \\ V_2(\alpha) \end{bmatrix} \quad (1.7)$$

By Picard's theorem (Chapter 1 and 2 of ref 1, the expressions (1.7) yields a unique solution $\phi(t) = (u(t)v(t)w(t)tx(t))^T$ depending analytically on λ .

This proves the theorem.

2. Construction of boundary condition vectors

We use the symbol

$$\begin{aligned} \varphi(a/x) &= u\left(\frac{a}{x}\right) v\left(\frac{a}{x}\right) w\left(\frac{a}{x}\right)^T \\ &= (uvw)^T(a, x) \end{aligned}$$

$(a, x \in [a, b])$ to denote a solution of (1.1) satisfying the following set of conditions:

$$\begin{aligned} (u(a/x))_{x=\alpha} &= u(a/a) = A_0 \\ (u'(a/x))_{x=\alpha} &= u'(a/a) = A_1 \\ (v(a/x))_{x=\alpha} &= v(a/x) = A_2 \end{aligned}$$

and

$$(w(a/x))_{x=\alpha} = w(a/x) = A_3$$

Where A_s ($s = 0, 1, 2, 3$) are arbitrary constants (real or complex).

Further, we use above symbols and

$$X_t(a/x) = u_t(a/x)v_t(a/x)w_t(a/x)^T$$

and

$$y_0(b/x) = \left(u_r\left(\frac{b}{x}\right) V_r\left(\frac{b}{x}\right) W_r\left(\frac{b}{x}\right)^T (r = 1 \text{ to } 4) \right)$$

be vector solution of (1.1) satisfying the conditions at $x = a$ and $x = b$ respectively as:

$$\begin{aligned} u_1(a/a) &= i, v_1(a/a) = 0, w_1(a/a) = 0, u'_1(a/a) = 0 \\ u_2(a/a) &= i, v_2(a/a) = i, w_2(a/a) = 0, u'_2(a/a) = 0 \\ u_3(a/a) &= 0, v_3(a/a) = i, w_3(a/a) = 0, u'_3(a/a) = 0 \\ u_4(a/a) &= 0, v_4(a/a) = 0, w_4(a/a) = 0, u'_4(a/a) = 0 \end{aligned}$$

to proof that $D(d) = Prs(d)$ is a real quantity.

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